# On solvability of certain non-standard elliptic problems 

Vladimir Vasilyev $\boldsymbol{N}$; Olga Chernova; Oksana Lukinova
Check for updates
AIP Conference Proceedings 2781, 020004 (2023)
https://doi.org/10.1063/5.0144767

## AIP Advances

Why Publish With Us?


# On Solvability of Certain Non-Standard Elliptic Problems 

Vladimir Vasilyev, ${ }^{\text {a) }}$ Olga Chernova, ${ }^{\text {b) }}$ and Oksana Lukinova ${ }^{\text {c }}{ }^{\text {( }}$<br>Applied Mathematics and Computer Modeling, Belgorod State National Research University, Belgorod, Russian Federation<br>${ }^{\text {a) }}$ Corresponding author: vladimir.b.vasilyev@gmail.com<br>b) chernova_olga@bsu.edu.ru<br>${ }^{\text {c) }}$ lukinova@bsu.edu.ru


#### Abstract

We consider a model elliptic pseudo-differential equation in a 4-wedge conical canonical 3D singular domain with two parameters. It is shown that the solution of a special boundary value problem for this equation can have a limit with respect to endpoint values of the parameters in appropriate Sobolev - Slobodetskii space if the boundary function is a solution of a special functional singular integral equation.


## INTRODUCTION

A lot of papers (see, for example, $[1,2,3]$ ) are devoted to constructing and developing the theory of elliptic pseudodifferential operators and equations on non-smooth manifolds or manifolds with non-smooth boundaries. The term "theory" means an existence in these stidies Fredholmness and index theorems.

Using the local principle and studying invertibility properties for model operators in so called canonical domains we at the same time investigate Fredholm properties for general elliptic pseudo-differential operators [4, 5, 6, 7]. Let us note that distinct model operators and canonical domains generate distinct Fredholm theories.

By canonical domain as usual we mean a certain cone in $m$-dimensional space. It may be a whole space $\mathbb{R}^{m}$, a half-space $\mathbb{R}_{+}^{m}=\left\{x \in \mathbb{R}^{m}: x=\left(x^{\prime}, x_{m}\right), x_{m}>0\right\}$ or a certain typical cone in $\mathbb{R}^{m}$.

Let $C$ be a convex cone in $\mathbb{R}^{m}$ non including a straight line. Let us consider a pseudo-differential operator of the following type

$$
(A u)(x)=\iint_{C} \int_{\mathbb{R}^{m}} A(\xi) e^{i(x-y) \cdot \xi} u(y) d \xi d y, \quad x \in C
$$

and a model equation

$$
\begin{equation*}
(A u)(x)=v(x), \quad x \in C, \tag{1}
\end{equation*}
$$

assuming that the symbol $A(\xi)$ of the operator $A$ satisfies the condition

$$
\begin{equation*}
c_{1}(1+|\xi|)^{\alpha} \leq|A(\xi)| \leq c_{2}(1+|\xi|)^{\alpha}, \alpha \in \mathbb{R} . \tag{2}
\end{equation*}
$$

We would like to remind that new approach to studying pseudo-differential equations on manifolds with a nonsmooth boundary was developed in [8]. It is based on studying invertibility conditions for a model pseudo-differential operator $A$ or conditions of unique solvability for the model equation (1) in appropriate functional spaces. To describe these conditions the concept of wave factorization for an elliptic symbol was used [8].

## ELLIPTIC EQUATION IN A MULTIDIMENSIONAL CONE

We will start from three-dimensional case. Let $C_{+}^{a b}$ be a conical canonical domain of the following type

$$
C_{+}^{a b}=\left\{x \in \mathbb{R}^{3}: x=\left(x_{1}, x_{2}, x_{3}\right), x_{3}>a\left|x_{1}\right|+b\left|x_{2}\right|, a, b>0\right\} .
$$

As usual $\tilde{A}(\xi)$ denotes symbol of the pseudo-differential operator $A$, it does not depend on a spatial variable $x$ and satisfies the condition (2). Here we remind some definitions from [9].

A radial tube domain over the cone $C_{+}^{a b}$ is called a domain in 3-dimensional complex space $\mathbb{C}^{3}$ of the following type

$$
T\left(C_{+}^{a b}\right) \equiv\left\{z \in \mathbb{C}^{3}: z=x+i y, x \in \mathbb{R}^{3}, y \in C_{+}^{a b}\right\}
$$

A conjugate cone $C_{+}^{* b}$ is called such a cone in which for all points the condition

$$
x \cdot y>0, \quad \forall y \in C_{+}^{a b}
$$

holds; $x \cdot y$ means inner product for $x$ and $y$.
According to [10] we introduce the wave factorization for a symbol.
Definition 1. Wave factorization of elliptic symbol $\tilde{A}(\xi)$ with respect to the cone $C_{+}^{a b}$ is called its representation in the form

$$
\tilde{A}(\xi)=\tilde{A}_{\neq}(\xi) \tilde{A}_{=}(\xi)
$$

where the factors $\tilde{A}_{\neq}(\xi), \tilde{A}_{=}(\xi)$ satisfy the following conditions:

1) $\tilde{A}_{\neq}(\xi), \tilde{A}_{=}(\xi)$ are defined everywhere excluding may be the points $\left\{\xi_{*} \in \mathbb{R}^{3}: \xi_{3}=\frac{1}{2 a}\left|\xi_{1}\right|+\frac{1}{2 b}\left|\xi_{2}\right|\right\}$;
2) $\tilde{A}_{\neq}(\xi), \tilde{A}_{=}(\xi)$ admit analytic continuation into radial tube domains $T\left(C_{+}^{a b}\right), T\left(-C_{+}^{a b}\right)$ respectively with estimates

$$
\begin{gathered}
\left|A_{\neq}^{ \pm 1}(\xi+i \tau)\right| \leq c_{1}(1+|\xi|+|\tau|)^{ \pm}, \\
\left|A_{=}^{ \pm 1}(\xi-i \tau)\right| \leq c_{2}(1+|\xi|+|\tau|)^{ \pm(\alpha-)}, \forall \tau \in C_{+}^{a b} .
\end{gathered}
$$

The real number is called an index of the wave factorization.
Remark 1. Everywhere below we assume that such a factorization exists.
We consider multidimensional equation (1) in analogous Sobolev-Slobodetskii space $H^{s}\left(C_{+}^{a b}\right)$ [10]. For simplicity we study the homogeneous equation

$$
\begin{equation*}
(A u)(x)=0, x \in C_{+}^{a b} . \tag{3}
\end{equation*}
$$

To describe a general solution of the equation (1) for the case $-s=1+\boldsymbol{\delta},|\boldsymbol{\delta}|<1 / 2$ we use some results from [11]. Further, we introduce the following singular integral operators [12, 13]

$$
\begin{aligned}
& \left(S_{1} u\right)\left(\xi_{1}, \xi_{2}, \xi_{3}\right)=v \cdot p \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{u\left(\tau, \xi_{2}, \xi_{3}\right) d \tau}{\xi_{1}-\tau} \\
& \left(S_{2} u\right)\left(\xi_{1}, \xi_{2}, \xi_{3}\right)=v \cdot p \frac{i}{2 \pi} \int_{-\infty}^{+\infty} \frac{u\left(\xi_{1}, \eta, \xi_{3}\right) d \eta}{\xi_{2}-\eta}
\end{aligned}
$$

and write

$$
\begin{gather*}
A_{\neq}(\xi) \tilde{u}(\xi)=\tilde{C}_{1}\left(\xi_{1}-a \xi_{3}, \xi_{2}-b \xi_{3}\right)+\tilde{C}_{2}\left(\xi_{1}-a \xi_{3}, \xi_{2}+b \xi_{3}\right) \\
+\tilde{C}_{3}\left(\xi_{1}+a \xi_{3}, \xi_{2}-b \xi_{3}\right)+\tilde{C}_{4}\left(\xi_{1}+a \xi_{3}, \xi_{2}+b \xi_{3}\right) \tag{4}
\end{gather*}
$$

where

$$
\begin{gathered}
\tilde{C}_{1}\left(\xi_{1}-a \xi_{3}, \xi_{2}-b \xi_{3}\right)=\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}-a \xi_{3}, \xi_{2}-b \xi_{3}\right)-\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}-a \xi_{3}, \xi_{2}-b \xi_{3}\right) \\
-\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}-a \xi_{3}, \xi_{2}-b \xi_{3}\right)+\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}-a \xi_{3}, \xi_{2}-b \xi_{3}\right)
\end{gathered}
$$

$$
\begin{gathered}
\tilde{C}_{2}\left(\xi_{1}-a \xi_{3}, \xi_{2}+b \xi_{3}\right)=\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}-a \xi_{3}, \xi_{2}+b \xi_{3}\right)-\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}-a \xi_{3}, \xi_{2}+b \xi_{3}\right) \\
+ \\
+\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}-a \xi_{3}, \xi_{2}+b \xi_{3}\right)-\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}-a \xi_{3}, \xi_{2}+b \xi_{3}\right) \\
\tilde{C}_{3}\left(\xi_{1}+a \xi_{3}, \xi_{2}-b \xi_{3}\right)=\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}+a \xi_{3}, \xi_{2}-b \xi_{3}\right)+\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}+a \xi_{3}, \xi_{2}-b \xi_{3}\right) \\
\\
\quad-\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}+a \xi_{3}, \xi_{2}-b \xi_{3}\right)-\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}+a \xi_{3}, \xi_{2}-b \xi_{3}\right) \\
\tilde{C}_{4}\left(\xi_{1}+a \xi_{3}, \xi_{2}+b \xi_{3}\right)=\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}+a \xi_{3}, \xi_{2}+b \xi_{3}\right)+\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}+a \xi_{3}, \xi_{2}+b \xi_{3}\right) \\
\\
+\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}+a \xi_{3}, \xi_{2}+b \xi_{3}\right)+\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}+a \xi_{3}, \xi_{2}+b \xi_{3}\right)
\end{gathered}
$$

To determine uniquely the arbitrary function $c_{0}\left(\xi_{1}, \xi_{2}\right)$ we require certain additional condition. for example, we assume that the restriction $\tilde{u}\left(\xi_{1}, \xi_{2}, 0\right)$ is given, i.e. the following integral

$$
\begin{equation*}
\int_{-\infty}^{+\infty} u\left(x_{1}, x_{2}, x_{3}\right) d x_{3} \equiv g\left(x_{1}, x_{2}\right) \tag{5}
\end{equation*}
$$

it gives the equality

$$
\begin{equation*}
\tilde{u}\left(\xi_{1}, \xi_{2}, 0\right)=\tilde{g}\left(\xi_{1}, \xi_{2}\right) \tag{6}
\end{equation*}
$$

Substituting (6) into (4) we obtain all summands. Indeed,

$$
\begin{gathered}
\tilde{A}_{\neq}(\xi) \tilde{u}(\xi)=\sum_{k=1}^{4} \tilde{C}_{k}\left(\xi_{1}, \xi_{2}\right) \\
=\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}, \xi_{2}\right)-\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)-\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)+\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right) \\
+\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}, \xi_{2}\right)-\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)+\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)-\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right) \\
+\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}, \xi_{2}\right)+\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)-\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)-\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right) \\
+\frac{1}{4} \tilde{c}_{0}\left(\xi_{1}, \xi_{2}\right)+\frac{1}{2}\left(S_{1} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)+\frac{1}{2}\left(S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)+\left(S_{1} S_{2} \tilde{c}_{0}\right)\left(\xi_{1}, \xi_{2}\right)=\tilde{c}_{0}\left(\xi_{1}, \xi_{2}\right)
\end{gathered}
$$

Taking into account the condition (6) we find

$$
\begin{equation*}
\tilde{c}_{0}\left(\xi^{\prime}\right)=\tilde{A}_{\neq}\left(\xi^{\prime}, 0\right) \tilde{g}\left(\xi^{\prime}\right) \tag{7}
\end{equation*}
$$

Theorem 1. Let $-s=1+\delta,|\delta|<1 / 2, g \in H^{s+1 / 2}\left(\mathbb{R}^{2}\right)$. Then the unique solution of the problem (3),(5) is given by the formula (4), and $c_{0}\left(x_{1}, x_{2}\right)$ is determined by the formula (7).

## DEGENERATED CASE

In the above section we have two parameters of the cone $a$ and $b$. Degenerated case corresponds to that case when one of the parameters (or both) tends to 0 or $+\infty$. Let us note that case $a, b \rightarrow 0$ was studied in [4], the cases $a \rightarrow 0, b=$ const and $a=$ const, $b \rightarrow 0$ were studied in [10]. Here we consider limit case $a \rightarrow+\infty, b=c o n s t$, the case $a=$ const,$b \rightarrow+\infty$ looks almost the same..

Starting point for this consideration will be the equality (4). We use the change of variables $\xi_{1}-a \xi_{3}=t_{1}, \xi_{1}+a \xi_{3}=$ $t_{3}$ from which we have $\xi_{1}=\frac{t_{3}+t_{1}}{2}, \xi_{3}=\frac{t_{3}-t_{1}}{2 a}$. So, we have new variables $t_{1}, \xi_{2}, t_{3}$. If we use the condition (5) we can find the unknown function $\tilde{c}_{0}$ by the formula (7). Now let us write the formula (4) for the new variables $t_{1}, \xi_{2}, t_{3}$. Then we obtain

$$
\begin{align*}
A_{\neq}\left(\frac{t_{2}+t_{1}}{2}, \xi_{2}, \frac{t_{3}-t_{1}}{2 a}\right) & \tilde{u}\left(\frac{t_{2}+t_{1}}{2}, \xi_{2}, \frac{t_{3}-t_{1}}{2 a}\right)=\tilde{C}_{1}\left(t_{1}, \xi_{2}-b \frac{t_{3}-t_{1}}{2 a}\right)+\tilde{C}_{2}\left(t_{1}, \xi_{2}+b \frac{t_{3}-t_{1}}{2 a}\right) \\
& +\tilde{C}_{3}\left(t_{3}, \xi_{2}-b \frac{t_{3}-t_{1}}{2 a}\right)+\tilde{C}_{4}\left(t_{3}, \xi_{2}+b \frac{t_{3}-t_{1}}{2 a}\right) \tag{8}
\end{align*}
$$

Tending $a$ to $+\infty$ we obtain the following relation

$$
A_{\neq}\left(\frac{t_{2}+t_{1}}{2}, \xi_{2}, 0\right) \tilde{u}\left(\frac{t_{2}+t_{1}}{2}, \xi_{2}, 0\right)=\tilde{C}_{1}\left(t_{1}, \xi_{2}\right)+\tilde{C}_{2}\left(t_{1}, \xi_{2}\right)+\tilde{C}_{3}\left(t_{3}, \xi_{2}\right)+\tilde{C}_{4}\left(t_{3}, \xi_{2}\right)
$$

After accurate calculations we find

$$
\tilde{C}_{1}\left(t_{1}, \xi_{2}\right)+\tilde{C}_{2}\left(t_{1}, \xi_{2}\right)+\tilde{C}_{3}\left(t_{3}, \xi_{2}\right)+\tilde{C}_{4}\left(t_{3}, \xi_{2}\right)=\frac{\tilde{c}_{0}\left(t_{1}, \xi_{2}\right)+\tilde{c}_{0}\left(t_{3}, \xi_{2}\right)}{2}-\left(S_{1} \tilde{c}_{0}\right)\left(t_{1}, \xi_{2}\right)+\left(S_{1} \tilde{c}_{0}\right)\left(t_{3}, \xi_{2}\right)
$$

Taking into account the condition (6), the formula (7) and new notation

$$
\tilde{A}_{\neq}\left(\xi_{1}, \xi_{2}, 0\right) \tilde{g}\left(\xi_{1}, \xi_{2}\right) \equiv h\left(\xi_{1}, \xi_{2}\right)
$$

we obtain the following equation with parameter $\xi_{2}$

$$
\begin{equation*}
h\left(\frac{t_{2}+t_{1}}{2}, \xi_{2}\right)=\frac{h\left(t_{1}, \xi_{2}\right)+h\left(t_{3}, \xi_{2}\right)}{2}-\left(S_{1} h\right)\left(t_{1}, \xi_{2}\right)+\left(S_{1} h\right)\left(t_{3}, \xi_{2}\right) \tag{9}
\end{equation*}
$$

Thus, we have the following property.
Theorem 2. If the symbol $A(\xi)$ admits the wave factorization with respect to $C_{+}^{a b}$ with the index such that $-s=$ $1+\boldsymbol{\delta},|\boldsymbol{\delta}|<1 / 2$ for enough large a then the unique solution of the boundary value problem (3),(5) has a limit under $a \rightarrow+\infty$ if and only if the boundary function $g \in H^{s+1 / 2}\left(\mathbb{R}^{2}\right)$ satisfies the equation (9).

## CONCLUSION

We have considered here a homogeneous equation only, it was done for simplicity. More general and more interesting situation is considering non-homogeneous equations. Some steps in this direction were suggested, but this approach should be verified.

## REFERENCES

1. J. V. Egorov and B.-W. Schulze, Pseudo-Differential Operators, Singularities, Applications (Birkhauser, Basel, 1997).
2. V. E. Nazaikinski, A. Y. Savin, B.-W. Schulze, and B. Y. Sternin, Elliptic Theory on Singular Manifolds (Chapman and Hall/CRC, Boca Raton, 2006).
3. B.-W. Schulze, B. Y. Sternin, and V. Shatalov, Differential Equations on Singular Manifolds; Semiclassical Theory and Operator Algebras (Wiley, Berlin, 1998).
4. G. Eskin, Boundar Value Problems for Elliptic Pseudodifferential Equations (Providence (RI): AMS, 1981).
5. V. B. Vasilyev, Math. Bohem. 139, 333-340 (2014).
6. V. B. Vasilyev, Adv. Dyn. Syst. Appl. 9, 227-237 (2014).
7. V. B. Vasilyev, Math. Meth. Appl. Sci. 41, 9252-9263 (2018).
8. V. B. Vasil'ev, Wave Factorization of Elliptic Symbols: Theory and Applications. Introduction to the Theory of Boundary Value Problems in Non-Smooth Domains (Kluwer Academic Publishers, Dordrecht-Boston-London, 2000).
9. V. S. Vladimirov, Methods of the Theory of Generalized Functions (Taylor \& Francis, 2002).
10. V. B. Vasilyev, Lobachevskii Journal of Mathematics 41, 917-925 (2020).
11. V. B. Vasilyev, Opusc. Math. 39, 109-124 (2019).
12. F. D. Gakhov, Boundary Value Problems (Dover Publications, Mineola, NY, 1981).
13. N. I. Muskhelishvili, Singular Integral Equations (North Holland, Amsterdam, 1976).
