# LINEAR CONJUGATION PROBLEM WITH A TRIANGULAR MATRIX COEFFICIENT 

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#### Abstract

We consider a classical linear conjugation problem for analytic vector-valued functions on a piecewise smooth curve with a triangular matrix coefficient in weighted Hölder spaces. In the twodimensional case, conditions for the existence of a solution are found, a solution of this problem is given, and the construction of the canonical matrix function is analyzed in detail.


Keywords and phrases: linear conjugation problem, weighted space, canonical function.
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Let us consider the classic linear conjugation problem

$$
\begin{equation*}
\phi^{+}-G \phi^{-}=g \tag{1}
\end{equation*}
$$

for analytic vector functions $\phi=\left(\phi_{1}, \ldots, \phi_{l}\right)$ with a triangular matrix coefficient $G$ given on a piecewise smooth curve $\Gamma$. This curve consists of a finite number of oriented smooth arcs, which can pairwise intersect only at their ends. The boundary values of $\phi^{ \pm}$are considered with respect to this orientation. The endpoints of these arcs form the set $F$ of the angular points of the curve.

For a sufficiently small $\rho>0$, the curve $\Gamma_{\tau}=\Gamma \cap\{|z-\tau| \leq \rho\}$ consists of several arcs $\Gamma_{\tau, j}$, $1 \leq j \leq n_{\tau}$, with the common end $\tau$. For definiteness, the numbering of these points is chosen in the order of going around the point $\tau$ counterclockwise. With respect to the orientation of the curve $\Gamma$, the $\operatorname{arc} \Gamma_{\tau, j}$ can either start or terminate at the point $\tau$; therefore, we assume that $\sigma_{\tau, j}=1$ or $\sigma_{\tau, j}=-1$, respectively. The curve $\Gamma$ divides the open circle $|z-\tau|<\rho$ into curvilinear sectors $S_{\tau, j}, 1 \leq j \leq n_{\tau}$, whose lateral sides are the arcs $\Gamma_{\tau, j}$ and $\Gamma_{\tau, j+1}$. For $n_{\tau}=1$, these sides coincide, that is, the set $S_{\tau}=S_{\tau, 1}$ is the circle with the cut along $\Gamma_{\tau}=\Gamma_{\tau, 1}$.

We use the notation used in [1] for weighted Hölder classes. As in [1], we assume that the matrix function $G$ is piecewise continuous and belongs to the class $C_{(+0)}^{\mu}(\Gamma, F)$, and its determinant $\operatorname{det} G$ is nonzero everywhere, including limit values

$$
(\operatorname{det} G)(\tau, j)=\lim _{\substack{t \in \Gamma_{, j, j} \\ t \rightarrow \tau}}(\operatorname{det} G)(t), \quad 1 \leq j \leq n_{\tau},
$$

at the angular points of the curve $\tau \in F$.
The problem (1) is considered in the weight class $C_{\lambda}^{\mu}(\hat{D}, F)$ of functions that are analytic in the open set $D=\mathbb{C} \backslash F$ whose components $\phi_{k}$ have finite orders at infinity satisfying the conditions

$$
\begin{equation*}
\operatorname{deg} \phi_{k} \leq n_{k}-1, \quad 1 \leq k \leq l, \tag{2}
\end{equation*}
$$

with given integers $n_{k}$. In other words, in a neighborhood of $\infty$, they behave as $O\left(|z|^{n_{k}-1}\right)$ or, equivalently, can be decomposed as follows:

$$
\phi_{k}(z)=\sum_{s \leq n_{k}-1} c_{j, s} z^{s} .
$$

[^0]The Riemann-Hilbert problem was exhaustively studied in the well-known monographs $[2,4,6]$ in the class $H^{*}$ of integrable functions $\phi$ belonging to $C_{\lambda}^{\mu}(\hat{D}, F)$ with some $\lambda>-1$ and $0<\mu<1$, in the class $H_{\varepsilon}$ of almost bounded functions, and in the class $H(\hat{D}, F)$ of bounded functions that belong, respectively, to $C_{\lambda}^{\mu}(\hat{D}, F)$ for all $\lambda<1$, and $C_{(+0)}^{\mu}(\hat{D}, F)$ with some $0<\mu<1$. However, various applications of this problem require the study of this problem in the space $C_{\lambda}^{\mu}$ for all weighted orders. For example, a similar situation occurs when considering the Riemann-Hilbert problem in simply connected domains with a piecewise smooth boundary using conformal mappings (see [3]), as well as when studying the problem of linear conjugation for polyanalytic functions.

Further, for simplicity, we restrict ourselves to the case $l=2$ where

$$
G=\left(\begin{array}{cc}
G_{1} & G_{0}  \tag{3}\\
0 & G_{2}
\end{array}\right)
$$

Since this matrix is triangular, the problem (1) is reduced to the successive solution of two scalar conjugation problems

$$
\begin{equation*}
\psi^{+}-G_{k} \psi^{-}=g, \quad k=1,2, \tag{4}
\end{equation*}
$$

in the class of functions $\psi \in C_{\lambda}^{\mu}(\hat{D}, F)$ satisfying the condition (2) at infinity.
For brevity, we write the Cauchy integral in the following form:

$$
(I \varphi)(z)=\frac{1}{2 \pi i} \int_{\Gamma} \frac{\varphi(t) d t}{t-z}, \quad z \notin \Gamma,
$$

which for $-1<\lambda<0$ defines a bounded operator $I: C_{\lambda}^{\mu}(\Gamma, F) \rightarrow C_{\lambda}^{\mu}(\hat{D}, F)$. Considering the branch of the logarithm $\ln G_{k}$ continuous on $\Gamma \backslash F$, which along with $G_{k}$ belongs to the class $C_{(+0)}^{\mu}(\Gamma, F)$, we introduce the function $h_{k}=I\left(\ln G_{k}\right)$, which vanishes at infinity, and its associated function

$$
\begin{equation*}
X_{k}(z)=e^{h_{k}(z)} \prod_{\tau}(z-\tau)^{-s_{\tau}}, \tag{5}
\end{equation*}
$$

with some integer $s_{\tau}$, which is canonical for the problem (4).
In the sectors $S_{\tau, j}$, the function $h_{k}$ can be represented as follows:

$$
h_{k}(z)=\frac{1}{2 \pi i}\left[\sum_{s=1}^{n_{\tau}} \sigma_{\tau, s}\left(\ln G_{k}\right)(\tau, s)\right] \ln (z-\tau)+h_{k, \tau, j}(z), \quad h_{k, \tau, j} \in C_{(+0)}^{\mu}\left(S_{\tau, j}, \tau\right) .
$$

Assume that

$$
\frac{1}{2 \pi} \arg \prod_{j=1}^{n_{\tau}}\left[G_{k}(\tau, j)\right]^{\sigma_{\tau, j}}=\alpha_{k, \tau}+i \beta_{k, \tau}, \quad 0 \leq \alpha_{k, \tau}<1
$$

so that

$$
\frac{1}{2 \pi i}\left[\sum_{s=1}^{n_{\tau}} \sigma_{\tau, s}\left(\ln G_{k}\right)(\tau, s)\right]=\alpha_{k, \tau}+i \beta_{k, \tau}+s_{k, \tau}
$$

with some integer $s_{k, \tau}$. Note that the sum on the left-hand side of $\tau$ coincides with the Cauchy index Ind $G_{k}$ of the function $G_{k}$, that is, with the sum of the increments of $\ln G_{k}$ on arcs that form the curve $\Gamma \backslash F$, which are taken in accordance with their orientation, divided by $2 \pi i$. Thus,

$$
\begin{equation*}
\operatorname{Ind} G_{k}=\sum_{\tau}\left(\alpha_{k, \tau}+i \beta_{k, \tau}+s_{k, \tau}\right) \tag{6}
\end{equation*}
$$

Obviously, the function $X_{k}$ in the sectors $S_{\tau, j}$ can be represented as follows:

$$
\begin{equation*}
X_{k}(z)=A_{k, \tau, j}(z)(z-\tau)^{\delta_{k, \tau}+i \beta_{k, \tau}}, \quad \delta_{k, \tau}=-s_{\tau}+s_{k, \tau}+\alpha_{k, \tau}, \tag{7}
\end{equation*}
$$

where $A, 1 / A \in C_{(+0)}^{\mu}\left(\hat{S}_{\tau, j}, \tau\right)$.

The integers $s_{\tau}$ in the definition (5) can be chosen arbitrarily; we choose them so that

$$
\begin{equation*}
\lambda \leq \delta_{k}<\lambda+1 \tag{8}
\end{equation*}
$$

with respect to the weighted order $\delta_{k}=\left(\delta_{k, \tau}, \tau \in F\right)$. Then

$$
\left[\alpha_{k, \tau}-\lambda_{\tau}\right]+s_{k, \tau}=s_{\tau},
$$

where $[x]$ means the integer part of $x$. Taking into account (6), we obtain

$$
\begin{equation*}
\lim _{z \rightarrow \infty} z^{\varkappa_{k}} X_{k}(z)=1, \quad \varkappa_{k}=\sum_{\tau}\left[\alpha_{k, \tau}-\lambda_{\tau}\right]+\operatorname{Ind} G_{k}-\sum_{\tau}\left(\alpha_{k, \tau}+i \beta_{k, \tau}\right) . \tag{9}
\end{equation*}
$$

Using the canonical function, it is easy to describe (see [1]) the solvability of the problem (4). For this, we denote the class of polynomials of degree $\leq \varkappa_{k}+n_{k}-1$ (for $\varkappa_{k}+n_{k} \leq 0$ by $P_{k}$, assume that $P_{k}=0$ ), and let $Q_{k}$ have a similar meaning with respect to polynomials of degree at most $-\left(\varkappa_{k}+n_{k}\right)-1$. Thus,

$$
\begin{array}{lll}
\operatorname{dim} P_{k}=\varkappa_{k}+n_{k}, & \operatorname{dim} Q_{k}=0 & \text { for } \varkappa_{k}+n_{k} \geq 0, \\
\operatorname{dim} P_{k}=0, & \operatorname{dim} Q_{k}=-\left(\varkappa_{k}+n_{k}\right) & \text { for } \varkappa_{k}+n_{k} \leq 0 .
\end{array}
$$

In all cases,

$$
\operatorname{dim} P_{k}-\operatorname{dim} Q_{k}=\varkappa_{k}+n_{k} .
$$

Theorem 1. Under the conditions

$$
\lambda_{\tau}-\alpha_{k, \tau} \notin \mathbb{Z}, \quad \tau \in F,
$$

the problem (4) is solvable in the class of functions $\psi \in C_{\lambda}^{\mu}(\hat{D}, F)$ satisfying the condition $\operatorname{deg} \psi \leq$ $n_{k}-1$ at infinity if and only if

$$
\left\langle\left(X^{+}\right)^{-1} g, q\right\rangle=0, \quad q \in Q_{k},
$$

where the following notation is introduced:

$$
\psi=X_{k} I\left[\left(X_{k}^{+}\right)^{-1} g\right]+X_{k} p, \quad p \in P_{k} .
$$

If this condition is fulfilled, then the general solution is given by the formula

$$
\psi=X_{k} I\left[\left(X_{k}^{+}\right)^{-1} g\right]+X_{k} p, \quad p \in P_{k} .
$$

Note that, according to (7), the multiplication operator $g \rightarrow\left(X_{k}^{+}\right)^{-1} g$ determines an isomorphism $C_{\lambda}^{\mu} \rightarrow C_{\lambda-\delta_{k}}^{\mu}$. Due to (9), the weighted order $\lambda_{k}=\lambda-\delta_{k}$ satisfies the condition $-1<\lambda_{k}<0$, so the operator $g \rightarrow X_{k} I\left[\left(X_{k}^{+}\right)^{-1} g\right]$ acting from $C_{\lambda}^{\mu}(\Gamma, F)$ to $C_{\lambda}^{\mu}(\hat{D}, F)$ is bounded. If the condition (9) is violated for some $\tau$, then we can only say that the function $\psi=X_{k} I\left[\left(X_{k}^{+}\right)^{-1} g\right]$ belongs to the class $C_{\lambda-0}^{\mu}$ (i.e., the class $C_{\lambda-\varepsilon}^{\mu}$ for any $\varepsilon>0$ ).

The theorem also implies that the index of the problem is $\operatorname{dim} P_{k}-\operatorname{dim} Q_{k}=\varkappa_{k}+n_{k}$.
Let us turn to the problem (1)-(3), for which we set

$$
\begin{equation*}
a=G_{0} X_{2}^{-}\left(X_{1}^{+}\right)^{-1} \tag{10}
\end{equation*}
$$

Due to (7), this function belongs to the class $C_{\delta_{2}-\delta_{1}}^{\mu}(\Gamma, F)$. According to (8), the weighted order $\delta_{2}-\delta_{1}$ lies strictly between -1 and 1 , so the function $a$ is integrable on $\Gamma$. Moreover, in this notation, we can introduce the polynomial classes

$$
\begin{equation*}
P_{2}^{0}=\left\{p \in P_{2} \mid\langle a p, q\rangle=0, q \in Q_{1}\right\}, \quad Q_{1}^{0}=\left\{q \in Q_{1} \mid\langle a p, q\rangle=0, p \in P_{2}\right\} . \tag{11}
\end{equation*}
$$

Lemma 1. In the decompositions

$$
\begin{equation*}
P_{2}=P_{2}^{0} \oplus P_{2}^{1}, \quad Q_{1}=Q_{1}^{0} \oplus Q_{1}^{1} \tag{12}
\end{equation*}
$$

the subspaces $P_{2}^{1}$ and $Q_{1}^{1}$ have a common dimension $r=\operatorname{dim} P_{2}^{1}=\operatorname{dim} Q_{1}^{1}$. Moreover, there exists a unique linear operator $R$, which to any integrable function $g \in L(\Gamma)$ on $\Gamma$ assign a polynomial $p=R g \in P_{2}^{1}$ with the following property:

$$
\begin{equation*}
\left\langle a p, q_{i}\right\rangle=\left\langle g, q_{i}\right\rangle, \quad 1 \leq i \leq r, \tag{13}
\end{equation*}
$$

where $q_{1}, \ldots, q_{r}$ is some basis in $Q_{1}^{1}$.
Proof. According to the definition (11), the bilinear form $\langle a p, q\rangle$ is nondegenerate on the product $P_{2}^{1} \times Q_{1}^{1}$ in the sense that the equations $\langle a p, q\rangle=0, q \in Q_{1}^{1}$, imply $p=0$ and, conversely, the equations $\langle a p, q\rangle=0, p \in P_{2}^{1}$, imply $q=0$. Hence the equality $\operatorname{dim} P_{2}^{1}=\operatorname{dim} Q_{1}^{1}$ is obtained directly.

Indeed, let the elements $p_{1}, \ldots, p_{s}$ and $q_{1}, \ldots, q_{r}$ form bases in $P_{2}^{1}$ and $Q_{1}^{1}$, respectively. Then, by virtue of the nondegeneracy property indicated above, rows and columns of the $(s \times r)$-matrix $A$ with elements $\left\langle a p_{i}, q_{j}\right\rangle$ are linearly independent, so this matrix is a square matrix.

Assuming that $p=\xi_{1} p_{1}+\ldots \xi_{r} p_{r} \in P_{2}^{1}$, we can write the system (13) as follows:

$$
\sum_{i=1}^{r} \xi_{i}\left\langle a p_{i}, q_{j}\right\rangle=\left\langle g, q_{j}\right\rangle, \quad j=1, \ldots, r .
$$

Since the matrix $A$ of this system is invertible, with respect to the inverse matrix $B=\left(B_{i j}\right)_{1}^{r}$ we arrive at the equation

$$
\xi_{i}=\sum_{j=1}^{r} B_{i j}\left\langle g, q_{j}\right\rangle,
$$

so we can set

$$
R g=\sum_{1 \leq i, j \leq r} B_{i j} p_{i}\left\langle g, q_{j}\right\rangle
$$

The uniqueness of the operator $R$ with the property (13) is almost obvious. Indeed, let $p \in P_{2}^{1}$ and $\left\langle a p, q_{i}\right\rangle=0,1 \leq i \leq r$. Then $\langle a p, q\rangle=0$ for all $q \in Q_{1}$ and, therefore, $p \in P_{1}^{0}$, which, according to the decomposition (12), is possible only for $p=0$.

Theorem 2. Let the conditions (9) hold for both values $k=1,2$ and let the function $g_{1}, g_{2} \in L(\Gamma)$ be determined by the equations

$$
\begin{equation*}
2 X_{1}^{+} g_{1}=2 f_{1}+G_{0} G_{2}^{-1}\left[-f_{2}+X_{2}^{+} S\left(X_{2}^{+}\right)^{-1} f g_{2}\right], \quad X_{2}^{+} g_{2}=f_{2} \tag{14}
\end{equation*}
$$

with the singular Cauchy operator $S$. The problem (1)-(3) is solvable in the class $C_{\lambda}^{\mu}(\hat{D}, F)$ of vectorvalued functions $\phi=\left(\phi_{1}, \phi_{2}\right)$ analytic in $D=\mathbb{C} \backslash \Gamma$ if and only if

$$
\begin{equation*}
\left\langle g_{1}, q\right\rangle=0, \quad q \in Q_{1}^{0} ; \quad\left\langle g_{2}, q\right\rangle=0, \quad q \in Q_{2} . \tag{15}
\end{equation*}
$$

If these conditions are fulfilled, then, in the notation of Lemma 1, the general solution of the problem is given by the formula

$$
\begin{equation*}
\phi_{1}=X_{1}\left[I\left(g_{1}-R g_{1}+p_{2}^{0}\right)+p_{1}\right], \quad \phi_{2}=X_{2}\left(I g_{2}-R g_{1}+p_{2}^{0}\right), \quad p_{1} \in P_{1}, p_{2}^{0} \in P_{2}^{0} \tag{16}
\end{equation*}
$$

with the operator $R$ from Lemma 1 .
Proof. We write the boundary condition (3) in the component-wise form

$$
\phi_{1}^{+}-G_{1} \phi_{1}^{-}=f_{1}+G_{0} \phi_{2}^{-}, \quad \phi_{2}^{+}-G_{2} \phi_{2}^{-}=f_{2},
$$

and consecutively apply Theorem 1 to the second and first equations. Then the necessary and sufficient conditions for the solvability of the problem take the following form:

$$
\begin{equation*}
\left\langle\left(X_{1}^{+}\right)^{-1}\left(f_{1}-G_{0} \phi_{2}^{-}\right), q\right\rangle=0, \quad q \in Q_{1} ; \quad\left\langle\left(X_{2}^{+}\right)^{-1} f_{2}, q\right\rangle=0, \quad q \in Q_{2}, \tag{17}
\end{equation*}
$$

If these conditions are fulfilled, then the solution is given by the formulas

$$
\begin{array}{ll}
\phi_{1}=X_{1} I\left[\left(X_{1}^{+}\right)^{-1}\left(f_{1}-G_{0} \phi_{2}^{-}\right)\right]+X_{1} p_{1}, & p_{1} \in P_{1}, \\
\phi_{2}=X_{2} I\left[\left(X_{2}^{+}\right)^{-1} f_{2}\right]+X_{2} p_{2}, & p_{2} \in P_{2} . \tag{18}
\end{array}
$$

From the last equation, according to the Sokhotski-Plemelj formula we have

$$
2 \phi_{2}^{-}=X_{2}^{-}\left[-\left(X_{2}^{+}\right)^{-1} f_{2}+S\left(X_{2}^{+}\right)^{-1} f_{2}\right]+2 X_{2}^{-} p_{2}=G_{2}^{-1}\left[-f_{2}+X_{2}^{+} S\left(X_{2}^{+}\right)^{-1} f_{2}\right]+2 X_{2}^{-} p_{2},
$$

so in the notation (10), (14) we get

$$
\begin{equation*}
\left(X_{1}^{+}\right)^{-1}\left(f_{1}-G_{0} \phi_{2}^{-}\right)=g_{1}+a p_{2} . \tag{19}
\end{equation*}
$$

As a result, the first relation in (17) takes the form

$$
\left\langle g_{1}+a p_{2}, q\right\rangle=0, \quad q \in Q_{1} .
$$

Obviously, it is equivalent to the pair of relations $\left\langle g_{1}, q\right\rangle=0, q \in Q_{1}^{0}$, and $\left\langle g_{1}+a p_{2}, q\right\rangle=0, q \in Q_{1}^{1}$. Assuming that $p_{2}=p_{2}^{0}+p_{2}^{1}, p_{2}^{j} \in P_{2}^{j}$, in the last equation we can replace $p_{2}$ by $p_{2}^{1}$. Due to Lemma 1 , we obtain that $p_{2}^{1}=-R g_{1}$. Together with the first relation, we arrive at the solvability condition (15) for $g_{1}$. At the same time, (19) turns into

$$
\left(X_{1}^{+}\right)^{-1}\left(f_{1}-G_{0} \phi_{2}^{-}\right)=g_{1}-R g_{1}+a p_{2}^{0}, \quad p_{2}^{0} \in P_{2}^{0} .
$$

Substituting this expression into (18), we obtain (16), which completes the proof of the theorem.
Note that the number of linearly independent orthogonality conditions in (15) is equal to $\operatorname{dim} Q_{1}^{0}+$ $\operatorname{dim} Q_{2}$. On the other hand, the formula (16) shows that the space of solutions of the homogeneous problem has the dimension $\operatorname{dim} P_{1}+\operatorname{dim} P_{2}^{0}$. Therefore, the index of the problem is equal to

$$
\varkappa(G)=\operatorname{dim} P_{1}+\operatorname{dim} P_{2}^{0}-\operatorname{dim} Q_{1}^{0}-\operatorname{dim} Q_{2} .
$$

According to (12) we have

$$
\operatorname{dim} P_{2}^{0}=\operatorname{dim} P_{2}-\operatorname{dim} P_{2}^{1}, \quad \operatorname{dim} Q_{2}^{0}=\operatorname{dim} Q_{2}-\operatorname{dim} Q_{2}^{1} .
$$

Substituting these expressions into the previous equality and taking into account the relation $\operatorname{dim} P_{2}^{1}=$ $\operatorname{dim} Q_{1}^{1}$, by virtue of Lemma 1, we obtain the equation

$$
\varkappa(G)=\sum_{k=1,2}\left(\operatorname{dim} P_{k}-\operatorname{dim} Q_{k}\right)=\varkappa_{1}+\varkappa_{2}-n_{1}-n_{2}
$$

for the index of the problem, similar to the scalar case.
The linear conjugation problem (1) in the space $C_{\lambda}^{\mu}$ with any weight order $\lambda$ can be solved with the help of the canonical matrix-valued function $X(z)$. The problem on the existence and asymptotics at the points $\tau \in F$ was examined in [5]. However, in the case (3) with a triangular matrix, this question is solved elementarily.

We search for the canonical matrix for this coefficient in a similar form:

$$
X=\left(\begin{array}{cc}
X_{1} & X_{0} \\
0 & X_{2}
\end{array}\right)
$$

then the relation $X^{+}=G X^{-}$for these matrices is reduced to the equation

$$
X_{0}^{+}=G_{1} X_{0}^{-}+G_{0} X_{2}^{-}
$$

for the unknown function $X_{0}$. This is an inhomogeneous conjugation problem; its solution can be written by the formula $X_{0}=X_{1} I\left[\left(X_{1}^{+}\right)^{-1} X_{2}^{-} G_{0}\right]$. Since $\left(X_{1}^{+}\right)^{-1} X_{2}^{-} G_{0} \in C_{\delta_{2}-\delta_{1}}^{\mu}(\Gamma, F)$ and by virtue of (8) and (9) the weight orders $\delta_{k}$ satisfy the condition $-1<\delta_{2}-\delta_{1}<1$, we conclude that the function $X_{0}$ in the sectors $S_{\tau, j}$ belongs to the classes

$$
X_{0}(z) \in \begin{cases}C_{\delta_{2}}^{\mu}\left(\hat{S}_{\tau, j}, \tau\right), & \delta_{2, \tau}<\delta_{1, \tau} \\ C_{\delta_{1}-0}^{\mu}\left(\hat{S}_{\tau, j}, \tau\right), & \delta_{2, \tau} \geq \delta_{1, \tau}\end{cases}
$$

Consequently,

$$
\begin{equation*}
X_{0} \in C_{\delta^{\prime}-0}^{\mu}(\hat{D}, F), \quad \delta_{\tau}^{\prime}=\min \left(\delta_{1, \tau}, \delta_{2, \tau}\right) \tag{20}
\end{equation*}
$$

and

$$
X^{-1}=\left(\begin{array}{cc}
X_{1}^{-1} & -X_{1}^{-1} X_{2}^{-1} X_{0}  \tag{21}\\
0 & X_{2}^{-1}
\end{array}\right) \in C_{\delta^{\prime \prime}-0}^{\mu}(\hat{D}, F), \quad \delta_{\tau}^{\prime \prime}=\max \left(\delta_{1, \tau}, \delta_{2, \tau}\right) .
$$

As in the scalar case, we can write the general solution of the problem (1), (3) in the class $C_{\lambda}^{\mu}$. Indeed, for the vector-valued function $\psi=X^{-1} \phi \in C_{\lambda-\delta^{\prime \prime}}^{\mu}(\hat{D}, F)$, we have the boundary-value problem $\psi^{+}-\psi^{-}=g$ with the right-hand side $g=\left(X^{+}\right)^{-1} f \in C_{\lambda-\delta^{\prime \prime}}^{\mu}(\Gamma, F)$. Since $-1<\lambda-\delta^{\prime \prime}<0$, its general solution has the form $\psi=I g+p$ with some polynomial vector $p=\left(p_{1}, p_{2}\right)$. It follows that

$$
\begin{equation*}
\phi=X I\left[\left(X^{+}\right)^{-1} f\right]+X p . \tag{22}
\end{equation*}
$$

Note that in the class $C_{\lambda}^{\mu}$, where $\lambda$ satisfies the condition (9), the problem (1), (3) is always solvable and its solution is given by the formula

$$
\phi_{1}=X_{1} I\left[\left(X_{1}^{+}\right)^{-1}\left(f_{1}+G_{0} \phi_{2}^{-}\right)\right], \quad \phi_{2}=I f_{2} .
$$

At the same time, this solution can be represented in the form (22), although the right-hand side of this formula, by virtue of (20), (21), belongs only to the class $C_{\lambda+\delta^{\prime}-\delta^{\prime \prime}}^{\mu}$.

The right-hand side of (22) satisfies the condition (2) if we impose the corresponding conditions on the function $f$ and the polynomial $p$; this leads to the description of the kernel and cokernel of the problem appearing in Theorem 2. According to [5], we can write the asymptotic representation for the matrix $X(z)$ in the sectors $S_{\tau, k}$ based on the spectral characteristics of the matrix

$$
G_{\tau}=\prod_{j=1}^{n_{\tau}}[G(\tau, j)]^{\sigma_{\tau, j}}
$$

where the order of the product corresponds to the order of arcs $\Gamma_{\tau, j}$ with a common start point $\tau$ passing counterclockwise. Using this asymptotics, we can show that in fact the formula (22) defines a solution in the class $C_{\lambda}^{\mu}$.

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